

# Conceptual design of discrete-event systems using templates

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PhD thesis

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# Motivation

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- Humans need tools to work with DESs
  - ◆ Very large state-space
  - ◆ Automatic generation of supervisors
- Need for better tools
  - ◆ Graphical environment not sufficient
    - Small mistakes may lead to completely incorrect solution
    - Not easy to modify or reuse models
    - Event synchronization is error-prone

# Outline of work

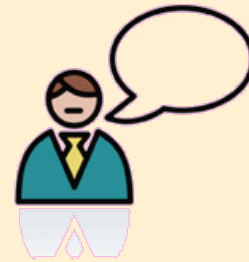
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- Observational study
  - ◆ How do people solve DES problems?
- Recommendations for DES software
- Template design
  - ◆ Theoretical framework
  - ◆ Tool implementation
- Evaluation of template design methodology
  - ◆ Are there positive effects in using the tool?

# Observation study

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- Five subjects
  - ◆ Graduate students with DES background
- Solve two problems
  - ◆ Familiar and unfamiliar (reformulated)
  - ◆ Using pen and paper and software
  - ◆ Think aloud
- Videotaped
- Protocol analysis



# Some findings (1)

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- Varied approaches
- Only one subject used recommended approach
- Manual construction of the supervisory solution
  - ◆ Sub-optimal
  - ◆ Passive control
  - ◆ No need for formal specifications
  - ◆ Simpler manual verification

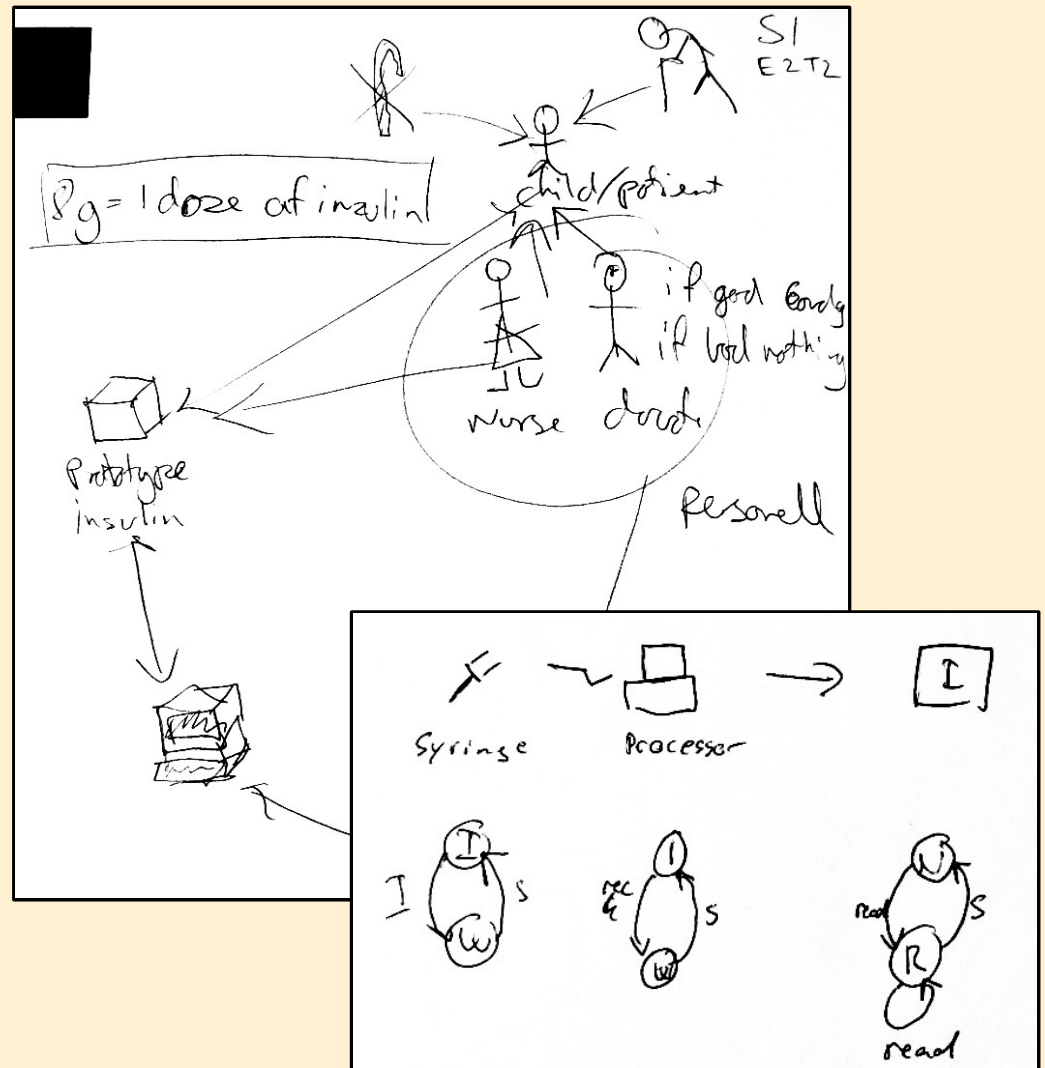
# Some findings (2)

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- Mistakes
  - ◆ Usually of poor judgement
  - ◆ Small errors that render the whole solution incorrect
- Frequent reference to
  - ◆ Problem description
  - ◆ Previous versions of models
    - ...even if incorrect

# Findings (3)

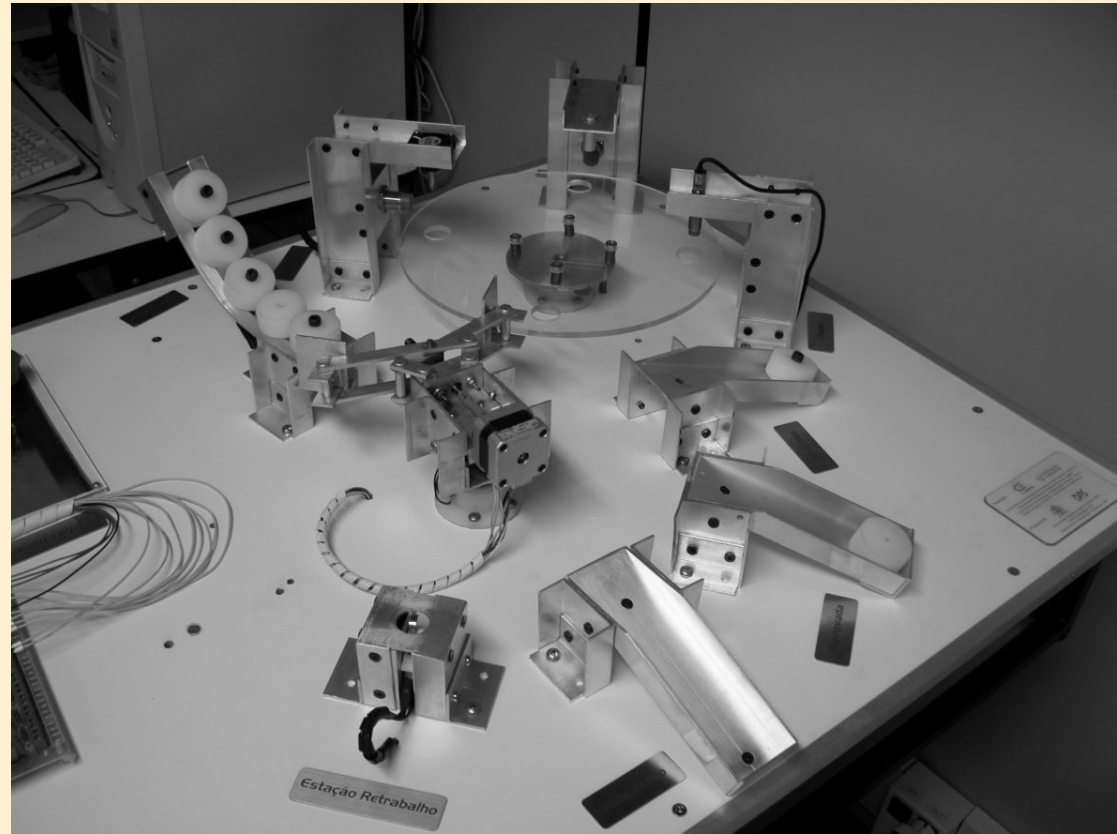
- System diagrams
- Synchronization of modules
  - ◆ Demanding
  - ◆ Error-prone
- Operations and relations considered at the high level of modelling



# Robotic testbed control

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- Frequent reconfiguration of model
- Changes in control specifications
- Need for PLC implementation of supervisor





# Conceptual design

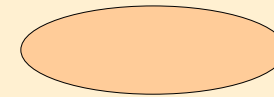
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- Active components



- ◆ Event generators

- Passive components



- ◆ Protocols between active components

- Connections between them



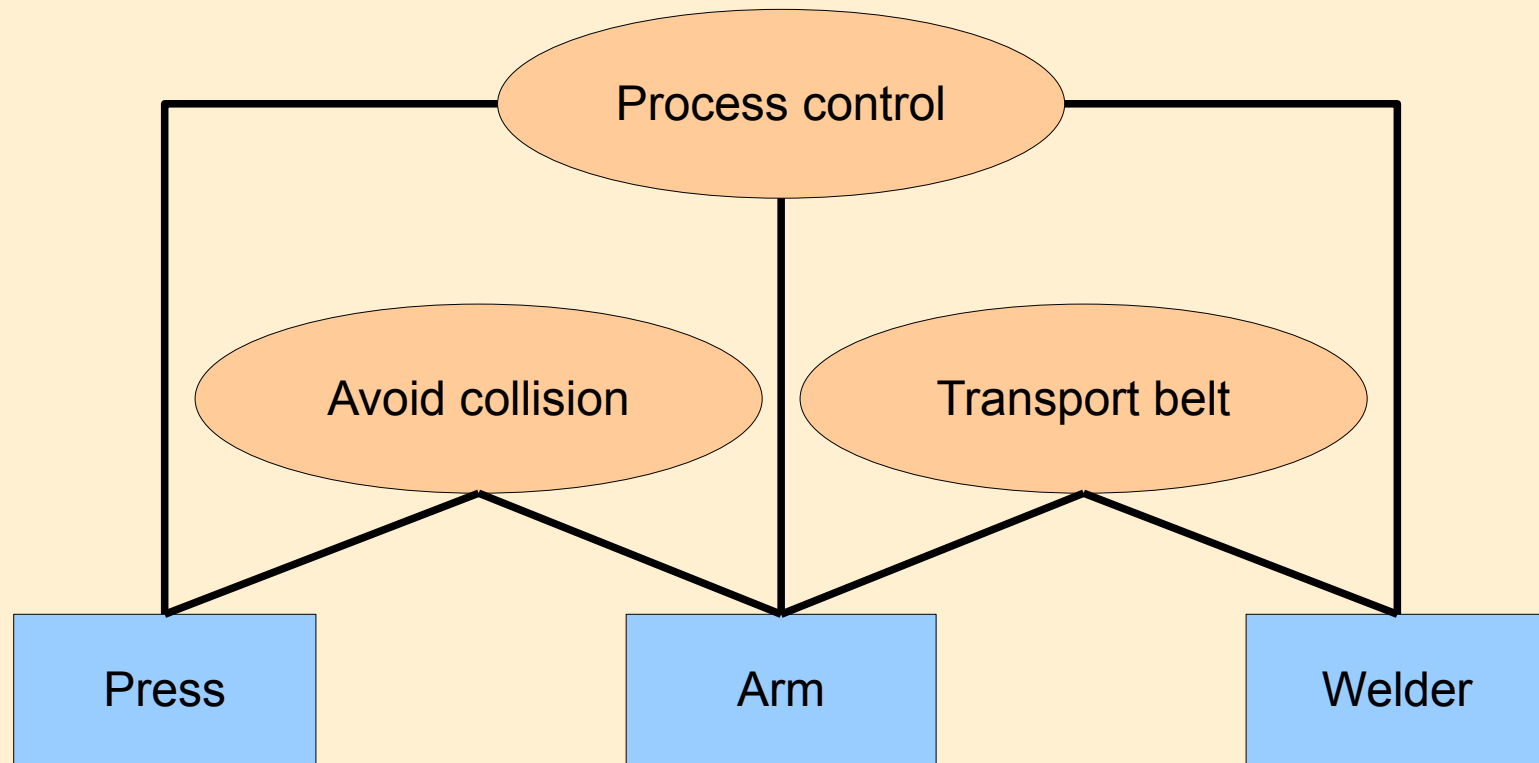
- ◆ Synchronization

- Simultaneous structural & functional design

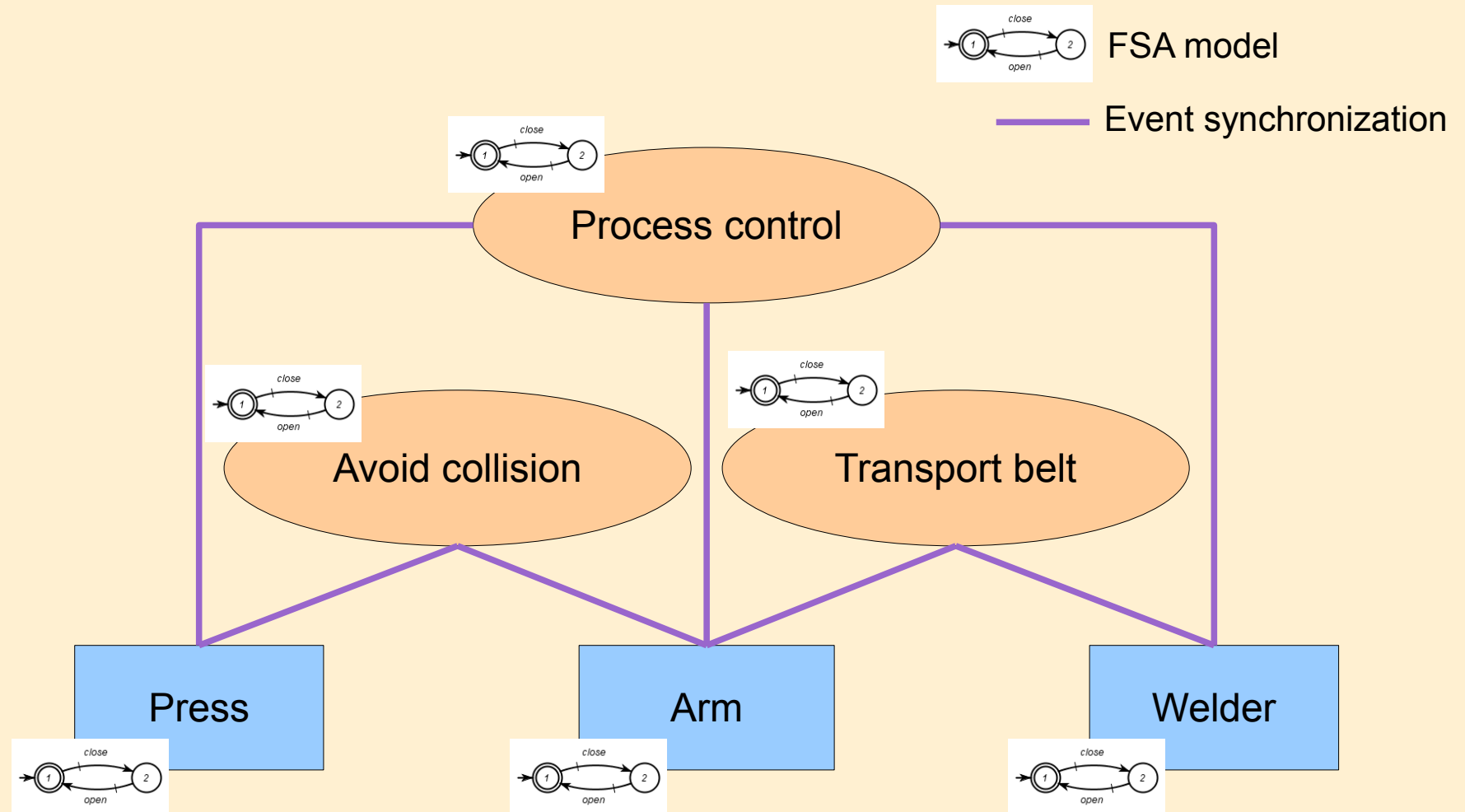
(Santos *et al.*, A computational model for supporting conceptual design of automatic systems, 2001)

# Example diagram

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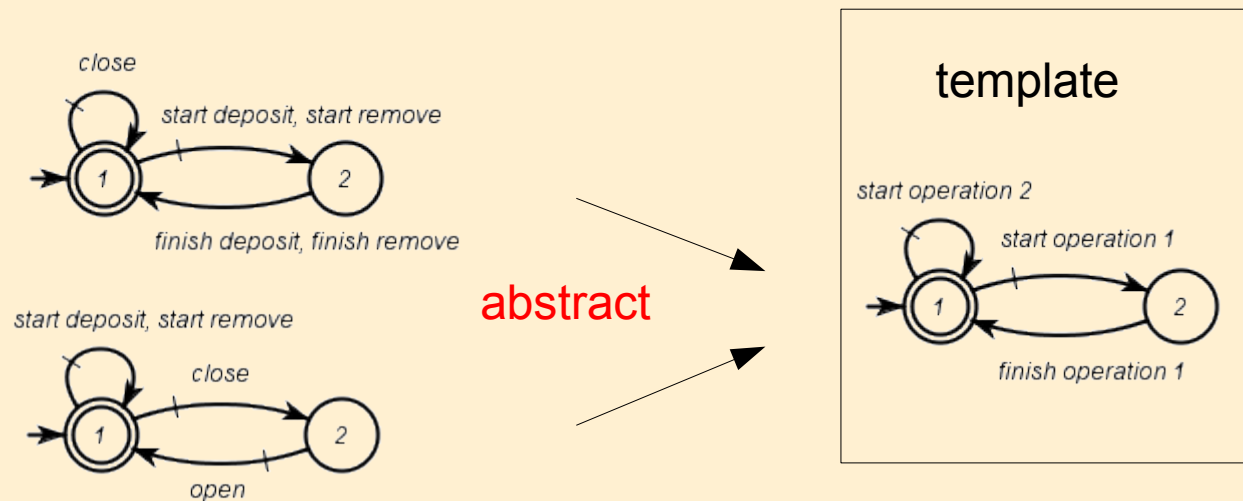


# Example diagram



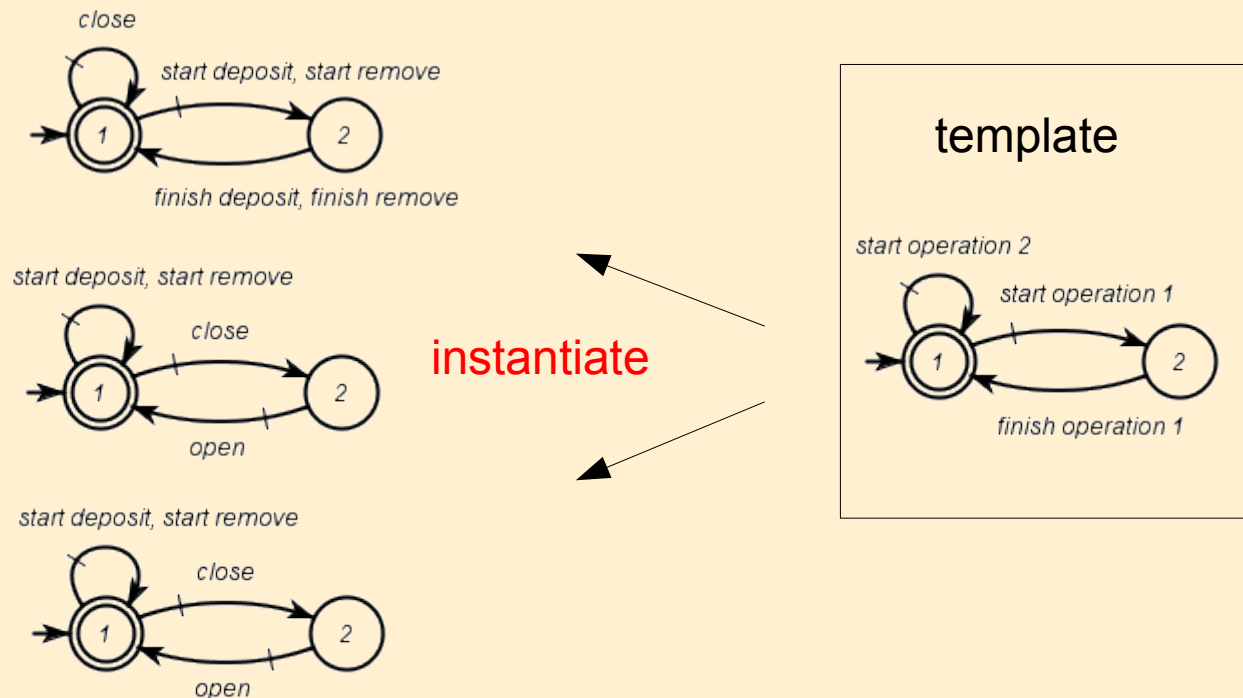
# Templates (abstract)

- Abstract common behavior



# Templates (instantiate)

- Instantiate existing templates



# Templates

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- Faster
  - ◆ No need to remodel similar behavior
  - ◆ Can reconfigure model as needed
- More robust
  - ◆ Can be thoroughly tested
  - ◆ Synchronization is independent of events
- Easier
  - ◆ Graphical conceptual designs
  - ◆ Sharing and reuse of existing models

# Template design implementation

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- Prototype implementation
  - ◆ Observed the user experience
  - ◆ PLC code generation
- Final implementation
  - ◆ Plugin for the IDEs software package
  - ◆ Reuse of FSA capabilities and existing algorithms
  - ◆ Take advantage of results in HCI

# Interface

The screenshot displays the IDE 3 beta 1 interface. The main window is titled "IDES 3 beta 1" and has a menu bar with "File", "Edit", "Operations", "Options", and "Help". Below the menu bar is a toolbar with various icons and a "Zoom: 100%" dropdown. The main workspace is divided into two panes: "Model" and "Consistency". The "Model" pane shows a Petri net diagram with the following elements:

- Station 1:** A red rectangle labeled "WS-T2".
- Channel:** An ellipse labeled "Input buffer".
- Link:** A line connecting Station 1 to the Channel, labeled "start=event1".
- Event:** A rectangle labeled "event2=start".
- Station 2:** A red rectangle labeled "WS-T2".
- Loop:** An ellipse labeled "LP2" connected to the event.

Red annotations point to these elements with labels: "List of consistency issues" (pointing to the Consistency pane), "Module (rectangle)" (pointing to Station 2), "Link" (pointing to the line between Station 1 and Channel), and "Channel (ellipse)" (pointing to the Input buffer). The "Drawing area" label is positioned below the diagram.

The "Consistency" pane is currently active and shows a "Library" tab with "Consistency issues", "Annotations", and "Notices" sub-tabs. The "Library with templates" section lists the following available templates:

- CL Client
- LP1 Loop (1 event)
- LP2 Loop (2 events)
- MUTEX Mutual exclusion
- SEQ2 Alternate two sequences
- WS-R Workstation type R
- WS-T2 Workstation type T2

Buttons for "Add", "Remove", "Edit", and "View model" are located at the bottom of the library pane. A small thumbnail of the current diagram is visible in the bottom-left corner of the IDE window, and the status bar at the bottom indicates "Untitled-0: 3 entities."



# Evaluation

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- Twelve subjects
  - ◆ Graduate students with DES background
  - ◆ From different research groups
- Solve two equivalent problems
  - ◆ Modify existing solution
  - ◆ Using IDES
  - ◆ With and without the template design environment

# Metrics

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- Rate of task completion
- Time of task completion
  - ◆ Time to supervisor computation
  - ◆ Total time
- Error rate
- Experiential confidence
- Experiential learnability
- System Usability Scale

# Results

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- Significant evidence that it is faster to use template designs
- No evidence for variety in
  - ◆ Error rate
  - ◆ Experiential confidence
  - ◆ Experiential learnability
- The SUS for template design is higher
- Subjects preferred the template design environment



# Contributions according to subjects

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- High-level structure
- (Handling of self-loops in the specifications)
- Templates
- Automation of modelling
- Modelling is less error-prone
- Speed of modelling
- Convenient user interface



# Conclusions

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- Observations of DES problem solving
  - ◆ Described new aspects of problem solving
  - ◆ Concretized suspected issues
- Template design environment
  - ◆ Reinterprets existing theories
  - ◆ Results in faster modelling
  - ◆ Supports the reuse of models
  - ◆ Provides a more enjoyable experience

# Future work

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- Longitudinal evaluation of template design
- Parametrization of templates
- Extension with other modelling frameworks
  - ◆ Petri nets, temporal logic, inequalities ...
- Better tools
  - ◆ Solution verification
  - ◆ Implementation of control solutions
  - ◆ Runtime computation of supervisory control

